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(54) Method of speech synthesis by means of concatenation and partial overlapping of waveforms

(57) Method for speech signal synthesis by means of time concatenation of waveforms representing elementary units of speech signal, in which: at least the waveforms associated to voiced sounds are subdivided into a plurality of intervals, corresponding to the responses of the vocal duct to a series of excitation impulses of the vocal cords, synchronous with the fundamental frequency of the signal; each interval is subjected to a weighting; the signals resulting from the weighting are replaced with a replica thereof shifted in time by an amount that depends on a prosodic information; and the synthesis is carried out by overlapping and adding the shifted signals. In each interval of original signal to be reproduced in synthesis, an unchanging part is identified, which contains the fundamental information and which is reproduced unaltered in the synthesized signal, and the operations of weighting, overlapping and adding involve only the remaining part of the interval.

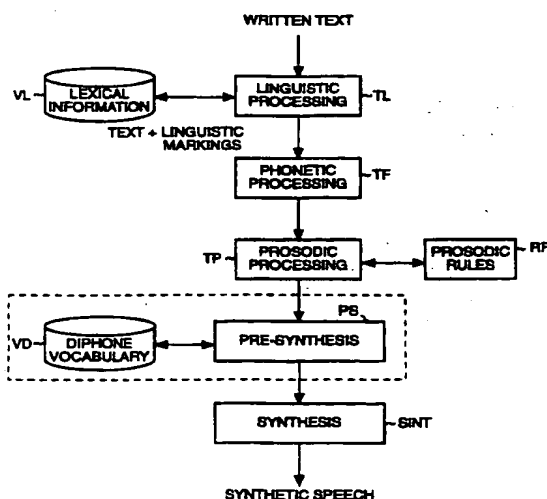


Fig. 1

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DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int.CL.6)
A	<p>ITOH ET AL.: "Phoneme segment concatenation and excitation control based on spectral distortion criterion for speech synthesis"</p> <p>INTERNATIONAL CONFERENCE ON SPOKEN LANGUAGE PROCESSING (ICSLP) 1990, vol. 1, 18 - 22 November 1990, KOBE, JP, pages 189-192, XP000503344</p> <p>* paragraph 4; figure 4 *</p> <p>---</p>	1	G10L5/04
A	<p>WO 85 04747 A (FIRST BYTE) 24 October 1985</p> <p>* page 17 - page 19, line 19; figures 10-13 *</p> <p>---</p>	1	<p>TECHNICAL FIELDS SEARCHED (Int.CL.6)</p> <p>G10L</p>
A	<p>WO 94 07238 A (EMERSON & STERN ASSOCIATES) 31 March 1994</p> <p>* page 41, line 28 - page 45, line 21 *</p> <p>---</p>	1	
A	<p>EP 0 155 970 A (SONY) 2 October 1985</p> <p>* page 17, line 16 - page 18; figure 7 *</p> <p>---</p>	1	
D,A	<p>MOULINES ET AL.: "Pitch-synchronous waveform processing techniques for text-to-speech synthesis using diphones"</p> <p>SPEECH COMMUNICATION, vol. 9, no. 5/6, 1 December 1990, AMSTERDAM, NL, pages 453-467, XP000202900</p> <p>* the whole document *</p> <p>---</p>	1	
A	<p>HIROKAWA ET AL.: "Segment selection and pitch modification for high quality speech synthesis using waveform sigments"</p> <p>INTERNATIONAL CONFERENCE ON SPOKEN LANGUAGE PROCESSING (ICSLP) 1990, vol. 1, 18 - 22 November 1990, KOBE, JP, pages 337-340, XP000503378</p> <p>* paragraph 3 *</p> <p>-----</p>	1	
The present search report has been drawn up for all claims			
Place of search		Date of completion of the search	Examiner
THE HAGUE		22 September 1997	Lange, J
<p>CATEGORY OF CITED DOCUMENTS</p> <p>X : particularly relevant if taken alone</p> <p>Y : particularly relevant if combined with another document of the same category</p> <p>A : technological background</p> <p>O : non-written disclosure</p> <p>P : intermediate document</p> <p>T : theory or principle underlying the invention</p> <p>E : earlier patent document, but published on, or after the filing date</p> <p>D : document cited in the application</p> <p>L : document cited for other reasons</p> <p>-----</p> <p>& : member of the same patent family, corresponding document</p>			

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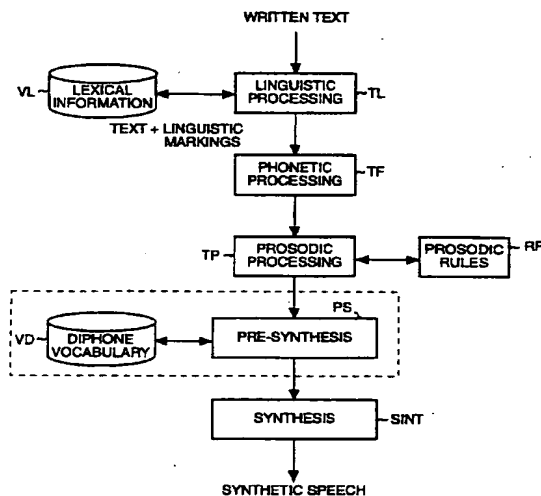


Fig. 1

Description

The invention described herein relates to speech synthesis and more particularly to a synthesis method based on the concatenation of waveforms related to elementary speech units. Preferably, but not exclusively, the method is applied to text-to-speech synthesis.

In these applications, a text to be transformed into a speech signal is first converted into a phonetic-prosodic representation, which indicates the sequence of corresponding phonemes and the prosodic characteristics (duration, intensity, and fundamental period) associated to them. This representation is then converted into a digital synthetic speech signal starting from a vocabulary of said elementary units, which in the most common case are constituted of diphones (voice elements extending from the stationary part of a phoneme to the stationary part of the subsequent phoneme, the transition between phonemes included). For the Italian language, a vocabulary of about one thousand diphones ensures the phonetic coverage, allowing all admissible sounds for Italian language to be synthesized.

In systems for text-to-speech synthesis, methods based on the concatenation, in the time domain, of the waveforms representing the various elementary units can be used for the generation of the speech signal: these methods are very flexible and guarantee good synthetic speech quality.

An example is described by E. Moulines and F. Charpentier in the paper "Pitch-synchronous waveform processing techniques for text-to-speech synthesis using diphones", Speech Communication, Vol. 9, No. 5/6, December 1990, pages 453-467. This method is based on the technique known as PSOLA (Pitch-Synchronous Overlap and Add), to apply the prosody imposed by the synthesis rules and concatenate the wave-forms of the elementary units. At least for the voiced segments of the original signal, the PSOLA technique carries out an analysis by applying a pitch-synchronous windowing, in particular by using Hanning windows whose duration is roughly twice the fundamental period (pitch period), thereby generating a sequence of partially overlapping short-term signals; in the synthesis phase, the signals resulting from the windowing are shifted in time synchronously with the fundamental period imposed by the prosodic rules for synthesis; finally, the synthetic signal is generated by overlapping and adding the shifted signals. To reduce computational complexity, the second step can be carried out directly in the time domain.

The complete windowing of the individual intervals of the original signal requires a relatively heavy computational load and moreover it constitutes an alteration of the original signal extending over the entire interval, so that the synthetic signal sounds less natural.

According to the invention, a synthesis method is provided in which that part of each interval of the original signal which contains the fundamental information is left unchanged, and only the remaining part of the interval is altered: this way, not only processing time is reduced, but the natural sounding of the synthetic signal is also improved, since the main part of the interval is the exact reproduction of the original signal.

The invention therefore provides a method for the speech signal synthesis by means of time-concatenation of waveforms representing elementary speech signal units, in which: at least the waveforms associated to voiced sounds are divided into a plurality of intervals, corresponding to the responses of the vocal duct to a series of impulses exciting the vocal cords synchronously with the fundamental frequency of the signal; the waveform in each interval is weighted; the signals resulting from the weighting are replaced with a replica thereof, shifted in time by an amount depending on a prosodic information; and the synthesis is carried out by overlapping and adding the shifted signals; and in which:

- a current interval of original signal to be reproduced in synthesis is subdivided into an unchanging part, which lies between the interval beginning and a left analysis edge represented by a zero crossing of the original speech signal that meets pre-determined conditions, and a changeable part, which lies between the left analysis edge and a right analysis edge essentially coinciding with the end of the current interval, the left and right analysis edges being associated, in the synthesized signal, respectively with a left and a right synthesis edge, of which the former coincides with the left analysis edge, with reference to a start-of-interval marker, and the latter coincides essentially with the end of the interval in the synthesized signal;
- a first connecting function, which has a duration equal to that of the segment of synthesized waveform lying between the left and right synthesis edges and an amplitude which decreases progressively and is maximum in correspondence with the left analysis edge, is applied on the part of waveform on the right of the left analysis edge of the current interval of original signal;
- a second connecting function, which has a duration equal to that of the segment of synthesized waveform lying between the left and right synthesis edges and an amplitude which increases progressively and is maximum in correspondence with the beginning of said subsequent interval, is applied on the part of waveform on the left of the subsequent interval of original signal to be reproduced synthetically;
- each interval of synthesized signal is built by reproducing unchanged the waveform in the unchanging part of the original interval and by joining thereto the waveform obtained by aligning in time and adding the two waveforms resulting from the application of the first and second connecting functions.

For the sake of further clarification, reference is made to the enclosed drawings, which illustrate an embodiment of the invention given by way of non-limiting example and where:

Figure 1 is the general outline of the operations of a text-to-speech synthesis system through concatenation of elementary acoustic units;

- Figure 2 is a diagram of the synthesis method through concatenation of diphones and modification of the prosodic parameters in the time domain, according to the invention;

- Figure 3 represents the waveform of a real diphone, with the markers for the phonetic and diphone borders and the pitch markers;

- Figures 4, 5 and 6 are graphs representing how the prosodic parameters of a natural speech signal are modified in some particular cases, according to the invention;

- Figures 7A, 7B, 8A, 8B, 9A, 9B, 10A and 10B are some real examples of application of the method according to the invention for the modification of the fundamental period on segments of the diphone in Figure 3;

- Figures 11 - 18 are flow charts of the operations for determining the left analysis and synthesis edge.

Before describing the invention in detail, the structure of a text-to-speech synthesis system is briefly described.

As can be seen in Figure 1, as a first phase the written text is fed to a linguistic processing stage TL which transforms the written text into a pronounceable form and adds linguistic markings: transcription of abbreviations, numbers, ..., application of stress and grammatical classification rules, access to lexical information contained in a special vocabulary VL. The subsequent stage, TF, carries out the transcription from orthographic sequence to the corresponding string of phonetic symbols. On the basis of a set of prosodic rules RP, the prosodic processing stage TP provides duration and fundamental period (and thus also fundamental frequency) for each of the phonemes leaving TF. This information is then provided to the pre-synthesis stage PS, which determines for each phoneme, the sequence of acoustic signals forming the phoneme (access to diphone data base VD) and, for each segment, how many and which intervals, with duration equal to the fundamental period, are to be used (in the case of voiced sounds) and the corresponding values of the fundamental period to be attributed in synthesis. These values are obtained by interpolating the values assigned in correspondence with the phoneme borders. In the case of unvoiced or "surd" sounds, in which there are no periodicity characteristics, the intervals have a fixed duration. This information is finally used by the actual synthesizer SINT which performs the transformations required to generate the synthetic signal.

Figure 2 illustrates in greater detail the operation of modules PS and SINT. The input is constituted by the current phoneme identifier F_i , by the phoneme duration D_i and by the values of the fundamental period P_{i-1} at the beginning of the phoneme and P_i at the end of the phoneme, and by the identifiers of the previous phoneme F_{i-1} and of the subsequent one F_{i+1} . The first operation to be performed is to decode diphones DF_{i-1} and DF_i and to detect the markers of diphone beginning and end and of phoneme border. This information is drawn directly from the data base or vocabulary storing diphones as waveforms and the related border, voiced/unvoiced decision and pitch marking descriptors. The subsequent module transforms said descriptors taking the phoneme as a reference. On the basis of this information, a rhythmic module computes the ratio between duration D_i imposed by the rule and the intrinsic duration of the phoneme (memorized in the vocabulary and given by the sum of the two portions of the phoneme belonging to the two diphones DF_{i-1} and DF_i). Then, taking into account the modification of the duration, it computes the number of intervals to be used in synthesis and determines the value of the fundamental period for each of them, by means of a law of interpolation between value P_{i-1} and P_i . The value of the fundamental period is then actually used only for voiced sounds, while for unvoiced sounds, as stated above, intervals are considered to be of fixed duration.

For the actual synthesis, the operations are different depending on whether the sound is voiced or unvoiced.

In the case of unvoiced sound, the synthesis demands a simple time shift (lengthening or shortening) of the aforesaid intervals on the basis of the ratio between the duration imposed by the prosodic rules and the intrinsic duration. In the case of voiced sound, instead, the method according to the invention is applied.

The synthesis method according to the invention starts from the consideration that a voiced sound can be considered as a sequence of quasi-periodic intervals, each defined by a value p_a of the fundamental period. This is clearly seen in Figure 3, which shows the waveform of diphone "à_m", the related markers separating individual intervals and, for each interval, value p_a of the corresponding period expressed in Hz. The part of Figure 3 between the two markers "v" corresponds to the right portion of phoneme "à"; the part between the second marker "v" and the end-of-diphone marker "f" corresponds to the left part of phoneme "m". The aforesaid intervals may be considered as the impulse responses of a filter, stationary for some milliseconds and corresponding to the vocal duct, which is excited by a sequence of impulses synchronous with the fundamental frequency of the source (vibrating frequency of the vocal cords). For each interval the synthesis module is to receive the original signal with fundamental period p_a (analysis period) and to provide a signal modified with period p_s (synthesis period) required by prosodic rules.

The essential information characterizing each speech interval is contained in the signal part immediately following the excitation impulse (main part of the response), while the response itself becomes less and less significant as the distance from the impulse position increases. Taking this into account, in the synthesis method according to the invention

this main part is maintained as unchanged as possible and the lengthening or shortening of the period required by the prosodic rules are obtained by acting on the remaining part.

For this purpose, an unchanging and a changeable part are then identified in each interval, and only the latter is involved in connection, overlap and add operations. The unchanging part of the original signal is not constant, but rather it depends for each interval on the ratio between p_s and p_a . This unchanging part lies between the start-of-interval marker and a so-called left analysis edge b_{sa} , which is one of the zero crossings of the original speech signal, identified with criteria that will be described further on and that can be different depending on whether the synthesis period is longer, shorter or equal to the analysis period. The changeable part is delimited by the left analysis edge b_{sa} and by a so-called right analysis edge b_{da} , which essentially coincides with the end of the interval, in particular with the sample preceding the start-of-interval marker of the subsequent interval.

In the synthesized signal, a left and a right synthesis edge b_{ss} , b_{ds} will correspond to the left and right analysis edge b_{sa} , b_{da} . For a given interval, the left synthesis edge obviously coincides with the left analysis edge, with reference to the start-of-interval marker, since the preceding part of signal is reproduced unaltered in the synthesis. The right synthesis edge is defined by relation

$$b_{ds} = b_{ss} + \Delta p \quad (1)$$

where $\Delta p = p_s - p_a$ will have a positive or negative value depending on whether, in synthesis, there is a lengthening or shortening of the fundamental period.

The changeable part of the interval is modified by applying a pair of connecting functions whose duration is $\Delta s = b_{ds} - b_{ss}$. The first function has a maximum value (specifically 1) in correspondence with the left analysis edge and a minimum value (specifically 0) in correspondence with the point $b_{sa} + \Delta s$. The second function has a maximum value (specifically 1) in correspondence with the right analysis edge b_{da} and a minimum value (specifically 0) in correspondence with point $b_{da} - \Delta s$. The connecting functions can be of the kind commonly used for these purposes (e.g. Hanning windows or similar functions).

For the sake of further clarifying the invention, Figures 4 - 6 show some graphs illustrating the application of the method to a fictitious signal. In these Figures, part A shows three consecutive intervals of the original signal, with indexes $i-1$, i , $i+1$, and indicates also their fundamental periods p_{ah} ($h = i-1, i, i+1$) as well as pitch (or start-of-interval) markers M_a and the left and right analysis edges b_{sa} , b_{da} . Parts B and C show, for each interval, respectively the first and second connecting functions (which hereinafter shall be called for the sake of simplicity "function B" and "function C") and the time relations with the original signal. Part D shows the synthesized signal waveforms resulting from the method according to the invention, with the indication of the respective fundamental periods p_{sk} ($k = j-1, j, j+1$), of pitch markers M_s and of left and right synthesis edges b_{ss} , b_{ds} . Part E is a representation of the waveform portion where, after the time shift, the waveforms obtained with the application of the two connecting functions to the changeable part of the original signal are submitted to the overlapping and adding process. Note that the serial numbers of the intervals in analysis and synthesis can be different, since suppressions or duplications of intervals may have occurred previously.

In particular, Figure 4 illustrates the case of an increase in fundamental period (and therefore decrease in frequency) in synthesis with respect to the original signal, in a signal portion where no interval suppressions or duplications have occurred. Weighting is carried out in each interval with a respective pair of connecting functions. As a consequence of the period increase, duration Δs of the functions is greater than the length of the variable part of the original signal, so that function B also interests the beginning of the waveform related to the subsequent interval, while function C interests a part of waveform on the left of the left analysis edge.

Figure 5 shows an analogous representation in the case of decrease in fundamental period (and therefore increase in frequency) in synthesis with respect to the original signal. In this example too no interval suppressions or duplications occurred. In this case functions B, C interest a waveform portion with shorter duration than the portion lying between b_{sa} and b_{da} .

Finally, Figure 6 shows an example of increase in fundamental period in synthesis in the case of suppression of an interval of the original signal (the one with index i in the example). Two intervals are obtained in synthesis, indicated by indexes $j-1$ and j , which intervals respectively maintain, as unchanging part, the one of intervals with index $i-1$ and $i+1$ in the original signal. The interval with index $i+1$ in the original signal is processed in the same way as each interval of original signal in Figure 4. The modified part of the interval with index $j-1$ in the synthesized signal, instead, is obtained by overlapping and adding the two waveforms obtained by weighting only with function B the changeable part of the interval with index $i-1$ in the original signal, and by weighting only with function C the final part of the interval with index i in the original signal. In other words, function B is applied on the right of b_{sa} in the current interval to be reproduced in synthesis, and function C is applied on the left of the subsequent interval to be reproduced. These procedures of application of the connecting functions are quite general and are applied also in case of interval duplication and diphone change.

Purely by way of example, for the diagrams in figures 4 - 6 the following functions were utilized:

$$0,5 - 0,5 \cdot \cos\{\pi[(\Delta s - 1 + b_{ss} - x_i)/(\Delta s - 1)]^n\} \quad (\text{function B})$$

$$0,5 - 0,5 \cdot \cos\{\pi[(x_i - b_{ss})/(\Delta s - 1)]^n\} \quad (\text{function C})$$

In these functions, b_{ss} , Δs have the meaning seen previously and are expressed as a number of samples; x_i is the generic sample of the variable part of the original waveform (with $b_{sa} \leq x_i < b_{sa} + \Delta s$, for function B, and $b_{da} - \Delta s \leq x_i < b_{da}$ for function C); n is a number which can vary (e.g. from 1 to 3) depending on ratio $\Delta s/p_a$: in particular, in the drawing, n was considered to be 1. Obviously, in the formulas, value 0.5 can be replaced by a generic value $A/2$ if a function whose maximum is A instead of 1 is used, or by a pair of values whose sum is 1 (or A).

Figures 7A, 7B to 10A, 10B represent some real examples of application of the method, for two portions of diphone "à_m" of Figure 3, utilized in two different positions in the sentence where the synthesis rules require respectively a decrease and an increase in fundamental period (and therefore an increase and respectively a decrease in fundamental frequency). For all intervals, pitch markers, left analysis and synthesis edges and fundamental frequency, both in analysis and synthesis, are indicated. Figures with letter A show the original waveform and Figures with letter B the synthesized signal. Figures 7A, 7B, 8A, 8B show the first two intervals of the diphone being examined (phoneme "à") in case of increase (Figures 7A, 7B) and respectively of decrease (Figures 8A, 8B) of the fundamental frequency. Figures 9A, 9B, 10A, 10B show instead the first two intervals of phoneme "m" in the same conditions as illustrated in Figures 7, 8. As an effect of the frequency decrease, only the first interval is completely visible in Figures 8B and 10B.

A preferred embodiment of the method adopted to identify the left analysis and synthesis edge for each interval to be reproduced in synthesis will now be described. In the example described, a different method is used depending on whether the fundamental period in synthesis is smaller than or equal to the period in analysis, or it is greater.

Figure 11 is the general flow chart of the operations carried out if $p_s \leq p_a$.

The first operation is the computation of function ZCR (Zero Crossing Rate) indicating the number of zero crossings (step 11). In this computation, zero crossings that are spaced apart from the previous one by less than a limited number of signal samples (e.g. 10) are neglected, in order to eliminate non-significant oscillations of the signal.

As can be seen in Figure 13, the zero crossings that are considered are assigned an index varying from 1 to the descriptor of the total zero crossing number LZV (step 110). Moreover, the following variables are assigned (step 111):

- b_{da} (right analysis edge) to the value of analysis period p_a ;
- b_{ds} (right synthesis edge) to the value of synthesis period $b_{da} + \Delta p$;
- Diff_a_s to the absolute value $|\Delta p|$ of the difference between the analysis and synthesis periods.

In these relations, as in those examined further on, the values of the periods and the lengths of certain intervals are expressed in terms of number of samples.

Going back to Figure 11, after computing function ZCR, a check is made (step 12) that the number of zero crossings found in step 11 is not lower than a minimal threshold of zero crossings IndZ_Min (e.g. 5 crossings). Actually, according to the invention, it is desired to reproduce unaltered, in the synthesized signal, the oscillations immediately following the excitation impulse, which oscillations, as stated, are the most significant ones. If the check yields a positive result, a possible candidate is searched among the zero crossings that were found (step 13) and subsequently a first phase of search for the left synthesis and analysis edges b_{ss} , b_{sa} is carried out (step 14). If at the end of step 14 no suitable zero crossing has been found, a search continuation phase is started (step 15) and, if after this phase the left synthesis and analysis edges have not yet been identified, then a phase of continuation and conclusion of the search is started (step 17). If the comparison in step 12 indicates that the number of zero crossings is lower than the threshold, then the zero crossing with index $J = \text{IndZ_Min}$ is arbitrarily considered as a candidate (step 18) and a search for b_{sa} and b_{ss} (step 19), identical to the one carried out in step 14, is performed: if this search is unsuccessful, then step 17, i.e. the search continuation and conclusion, is directly started, without going through step 15, for reasons that will become clear when the latter is described.

A step analogous to step 17 is envisaged also in case of lengthening of the fundamental period in synthesis, as will be seen further on. For the sake of simplicity, the same flow chart was used for both cases, which are distinguished by means of some conditions of entry into the step itself. In particular, for the case $p_s \leq p_a$ the conditions $r_P \leq 1$ (where r_P is the ratio p_s/p_a), Start = 0, End = LZV, Step = +1 (step 16 in Figure 11) are set. The first condition is evident. The other three indicate that the cycle of examination of the zero crossings envisaged in phase 17 will be carried out in the order of increasing indexes.

The operations performed in steps 13-15 and 17 will be described in detail further on, with reference to Figures 14 - 17.

Figure 12 is the general flow chart of the operations carried out if the synthesis period p_s is longer than the analysis period p_a . The first operation (step 21) consists again in computing function ZCR and is identical to step 11 in Figure

11. Subsequently (step 22) a search is carried out for the left synthesis and analysis edges, with procedures that will be described with reference to Figure 18, and, if this phase does not have a positive outcome, a search continuation and conclusion phase is initiated (step 24), corresponding to step 17 in Figure 11. Conditions $r_P > 1$, $\text{Start} = \text{LZV}-1$, $\text{End} = -1$, $\text{Step} = -1$ are set for the operations envisaged in step 24. The first condition is evident. The other three indicate that the cycle of examination of the zero crossings envisaged in step 24 will be carried out in this case in the order of decreasing indexes.

Figure 14 shows the flow chart of the search for a zero crossing which is candidate to act as left analysis and synthesis edge (step 13 in Figure 11). J denotes the index of the candidate. In particular, the central zero crossing, whose index is $J = (\text{LZV}+1)/2$ (step 130), is initially examined as a candidate and its abscissa $\text{ZCR}(J)$ is compared with the right synthesis edge b_{ds} (step 131). If this initial candidate is already on the left of the right synthesis edge, the phase of search for the left analysis and synthesis edge (step 14, Figure 11) is started directly. In the opposite case, zero crossings on the left of the central one are examined with a backwards cycle, searching for a candidate whose abscissa is on the left of b_{ds} (steps 132-134). When a zero crossing that meets this condition is found, it is considered as a candidate (step 135) and the search phase (step 14 in Figure 11) is started after verifying that the index of the candidate is not $(\text{LZV}+1)/2$ (step 136). In effect, a backward search cycle has been performed because the initial candidate, with index $(\text{LZV}+1)/2$, was on the right of b_{ds} , and hence obtaining a candidate with that index signals an anomalous condition: if this occurs, the search phase is started after setting $J=0$. The same operations are performed if the cycle ends before a candidate is found.

Figure 15 shows the operations carried out for the first phase of search for b_{ss} , b_{sa} (step 14 in Figure 11). For this search, a backward examination is made of the zero crossings starting from the one preceding LZV, and the distance Diff_z_a between the right analysis edge b_{da} and the current zero crossing $\text{ZCR}(i)$ is calculated (steps 140, 141). This distance, multiplied by r_P (ratio between the synthesis period p_s and the analysis period p_a) is compared with Diff_a_s (step 142), to check that there is a time interval sufficient to apply the connecting function. Weighting with r_P links the duration of that function to the percentage shortening of the period and it is aimed at guaranteeing a good connection between subsequent intervals. If $\text{Diff_a_s} > \text{Diff_z_a} \cdot r_P$, the search cycle continues (step 143), until a zero crossing is found such that $\text{Diff_a_s} \leq (\text{Diff_z_a} \cdot r_P)$ or until all zero crossings have been considered: in the latter case step 14 is ended and step 15 (Figure 11) of search continuation, is started. When the condition $\text{Diff_a_s} \leq \text{Diff_z_a} \cdot r_P$ is met, the current index i is compared with index J of the candidate (step 144). If $i < J$, the cycle is continued. If the two indexes are equal, then the current zero crossing is considered as left analysis edge b_{sa} and as left synthesis edge b_{ss} (step 147); if instead $i > J$, then distance Δ_a between the right analysis edge b_{da} and the current zero crossing $\text{ZCR}(i)$, distance Δ_s between the right synthesis edge b_{ds} and the current zero crossing $\text{ZCR}(i)$, and ratio Δ between Δ_s and Δ_a are calculated (step 145), and ratio Δ is compared to the value $(r_P)/2$ (step 146). If $\Delta \leq (r_P)/2$, then the tasks of left analysis edge b_{sa} and left synthesis edge b_{ss} are assigned to the current zero crossing (step 147), otherwise phase 15 (Figure 11) of search continuation is started. The last comparison indicates that not only a sufficient distance between the left and right synthesis edge is required, but also that the connecting function takes into account the shortening in synthesis; this, too, helps obtaining a good connection between adjacent intervals.

Variable "TRUE" in the last step 147 in Figure 15 indicates that b_{sa} and b_{ss} have been found and disables subsequent search phases. The same variable will also be utilized with the same meaning in the other flow charts related to the search for the left analysis and synthesis edges.

Step 14 allows finding a candidate, if any, that lies on the left of the right synthesis edge and is as close as possible to it, while guaranteeing a time interval sufficient to apply the connecting function; this step is the core of the criterion of the search for b_{sa} and b_{ss} .

Search continuation step 15 is illustrated in detail in Figure 16. This step, if it is performed (negative result of phase 14 and therefore of the check on the TRUE condition in step 150), starts with a new comparison between LZV and IndZ_min (step 151), aimed now at just verifying whether $\text{LZV} > \text{IndZ_min}$. If the condition is not met, then step 17, of search continuation and conclusion is initiated. If $\text{LZV} > \text{IndZ_min}$, then a check is made on whether the zero crossing having index IndZ_min is positioned on the left of the right synthesis edge b_{ds} (step 152). In the affirmative, this crossing is considered to be the left analysis edge b_{sa} and left synthesis edge b_{ss} (step 153). If instead the zero crossing having index IndZ_min is still on the right of the right synthesis edge, then step 17 (Figure 11) of search continuation and conclusion is initiated.

Search continuation and conclusion step 17 is represented in detail in Figure 17. After checking the need to perform it (step 170), the zero crossings are reviewed again, in increasing index order. In the examination cycle (steps 171 - 174 in Figure 17), a check is made at each step on whether the current zero crossing (indicated by Z_tmp) is on the left of the right synthesis edge b_{ds} and its distance from such edge is not lower than a predetermined minimum value δ , e.g. 10 signal samples (step 173). If the two conditions are not met, then the subsequent zero crossing is examined (step 174), otherwise this zero crossing is temporarily considered as the left synthesis and analysis edge (step 175) and the cycle is continued. The last zero crossing that meets condition 173 will be considered as the left synthesis and analysis edge (step 179). The check on r_P at step 176 is an additional means to distinguish between the case $p_s \leq p_a$ and the case $p_s > p_a$, and it causes steps 177 and 178 of the flow chart to be omitted in the case being examined.

Figure 18 illustrates the search for b_{sa} and b_{ss} when the synthesis period is lengthened with respect to the analysis period. This search starts with a comparison between the lengthening in synthesis Diff_a_s and half the duration of the analysis period p_a (step 220). If $\text{Diff_a_s} > p_a/2$, step 24 (illustrated in detail in Figure 17) is started directly. If $\text{Diff_a_s} \leq p_a/2$, a backward search cycle is carried out, starting from the zero crossing preceding LZV. Distance Diff_z_a between the right analysis edge b_{da} and the current zero crossing ZCR(i) (steps 221, 222) is calculated and is compared with Diff_a_s (step 223): if it is smaller, then the search cycle continues (step 224), otherwise the current zero crossing is considered as the left analysis and synthesis edge (step 225). If, at the end of the cycle, b_{sa} and b_{ss} have not been determined, then the phase of search continuation and conclusion is initiated (phase 24, Figure 12).

If the lengthening required in synthesis is less than or equal to half the analysis period, the operations described above allow finding a candidate, if any, that is the first for which the distance from the right analysis edge exceeds or is equal to the required lengthening.

In the search continuation and conclusion phase, a backward search cycle is carried out, as stated, starting from the zero crossing preceding LZV, with the procedures illustrated in steps 171 - 175 in Figure 17. Moreover, since a lengthening of the interval is considered (step 176), distance Δ_a between the right analysis edge b_{da} and the current zero crossing Z_Tmp , distance Δ_s between the right synthesis edge b_{ds} and the current zero crossing Z_Tmp and ratio Δ between these distances are computed (step 177) for the zero crossings that meet the conditions of step 173. Ratio Δ is compared with twice the ratio between the periods (r_P*2) for the same reasons seen for comparison 146 in Figure 15, and the zero crossing that meets the condition $\Delta \leq (r_P*2)$ will be taken as left analysis edge b_{sa} and left synthesis edge b_{ss} .

The conditions imposed in this phase allow assigning the task of left analysis edge to a zero crossing that lies on the left of the right synthesis edge, is as close as possible to it and also guarantees a sufficient time interval for the connecting function to be applied: in particular, given a certain analysis period, a left analysis edge positioned farther back in the original period will correspond to a greater lengthening required in synthesis.

The method described herein can be performed by means of a conventional personal computer, workstation, or similar apparatus.

It is evident that what is described above is given by way of non-limiting example and that variations and modifications are possible without departing from the scope of the invention.

Claims

1. Method for speech signal synthesis by means of time concatenation of waveforms representing elementary speech signal units, in which: at least the waveforms associated to voiced sounds are subdivided into a plurality of intervals, corresponding to the responses of the vocal duct to a series of impulses of vocal cord excitation, synchronous with the fundamental frequency of the signal; the waveform in each interval is weighted; the signals resulting from the weighting are replaced with a replica thereof shifted in time by an amount depending on a prosodic information; and synthesis is performed by overlapping and adding the shifted signals; characterized in that:

- a current interval of original signal to be reproduced in synthesis is subdivided into an unchanging part, which lies between the interval beginning and a left analysis edge represented by a zero crossing of the original speech signal which meets predetermined conditions, and a variable part, which lies between the left analysis edge and a right analysis edge that essentially coincides with the end of the current interval, the left and right analysis edges being associated, in the synthesized signal, respectively with a left synthesis edge and a right synthesis edge, of which the former coincides with the left analysis edge, with reference to a start-of-interval marker, and the latter coincides essentially with the end of the interval in the synthesized signal;
- a first connecting function is applied on the part of waveform on the right of the left analysis edge of the current interval of original signal, which function has a duration equal to that of the segment of synthesized waveform lying between the left and right synthesis edges and an amplitude that progressively decreases and is maximum in correspondence with the left analysis edge;
- a second connecting function is applied on the part of waveform on the left of the subsequent interval of original signal to be reproduced in synthesis, which function has a duration equal to that of the segment of synthesized waveform lying between the left and right synthesis edges and an amplitude that progressively increases and is maximum in correspondence with the beginning of said subsequent interval;
- each interval of synthesized signal is built by reproducing unchanged the waveform in the unchanging part of the original interval and by joining thereto the waveform obtained by aligning in time and adding the two waveforms resulting from applying the two connecting functions.

2. Method according to claim 1, characterized in that, if the duration of an interval is reduced or maintained unchanged for the synthesis with respect to the duration of the corresponding interval of the original signal, the left analysis edge and the left synthesis edge are determined with the following operations:

- computing the number of zero crossings of the original signal waveform and assigning each zero crossing an index, increasing from the beginning towards the end of the interval;
- checking that the number of zero crossings is not lower than a first threshold;
- searching, in case of positive outcome of the check, for a zero crossing candidate to act as left analysis and synthesis edge;
- backwards searching, among all zero crossings in the interval, except the last one, for a candidate that lies on the left of the right synthesis edge, is as close as possible to it and guarantees a time interval sufficient for the connecting functions to be applied, and assigning the task of left analysis and synthesis edge to this candidate.

3. Method according to claim 2, characterized in that, in said computation of the zero crossings, zero crossings whose distance from the previous one is lower than a predetermined distance are not taken into consideration.

4. Method according to claim 2 or 3, characterized in that, if the backwards search has yielded a negative result and if the number of zero crossings is higher than the first threshold, the tasks of left analysis edge and left synthesis edge are assigned to the zero crossing whose index corresponds to said threshold, if such a zero crossing lies on the left of the right synthesis edge.

5. Method according to any of claims 2 to 4, characterized in that if the backwards search has yielded a negative result and if the number of zero crossings is not higher than the first threshold, a further search phase is carried out to identify the zero crossings lying on the left of the right synthesis edge and having a distance from the latter that is not lower than a second threshold, and the tasks of left analysis edge and right analysis edge are assigned to the highest index zero crossing which meets these conditions.

6. Method according to any of claims 2 to 5, characterized in that, if the comparison with the first threshold indicates that the number of zero crossings is lower than the first threshold, said backwards search is performed directly and, if it yields negative a result, said further search phase is performed directly.

7. Method according to any of claims 1 to 6, characterized in that, if the duration of the interval is increased for the synthesis compared to the duration of the corresponding interval of the original signal, the left analysis edge and the right synthesis edge are determined with the following operations:

- computing the number of zero crossings of the original signal waveform;
- comparing the duration lengthening of the synthesis interval and the duration of the original interval, to check that the lengthening does not exceed half the original interval duration;
- if the check yields a positive result, searching backwards, among all the zero crossings except the last one, for a candidate zero crossing that lies on the left of the right synthesis edge and is the first for which the distance from the right synthesis edge is not shorter than the lengthening of the interval duration, the tasks of left analysis edge and left synthesis edge being assigned to the zero crossing that meets said condition, if any.

8. Method according to claim 7, characterized in that, in said computation of the zero crossings, the crossings whose distance from the previous crossing is lower than a predetermined distance are not taken into consideration.

9. Method according to claim 7 or 8, characterized in that, if the interval duration lengthening exceeds half the original interval duration or if the backwards search is unsuccessful, a further backwards search phase is carried out to identify the zero crossings lying on the left of the right synthesis edge and having a distance from the latter that is not lower than a third threshold; the distances from the right synthesis edge and from the right analysis edge and the ratio between these distances are computed for such zero crossings; said ratio is compared with the value of the ratio between the duration of the synthesis interval and the duration of the original interval, and the tasks of left analysis edge and left synthesis edge are assigned to the zero crossing whose index is the lowest among those for which the ratio between the distances from the edges does not exceed by more than a predetermined factor the ratio between durations.

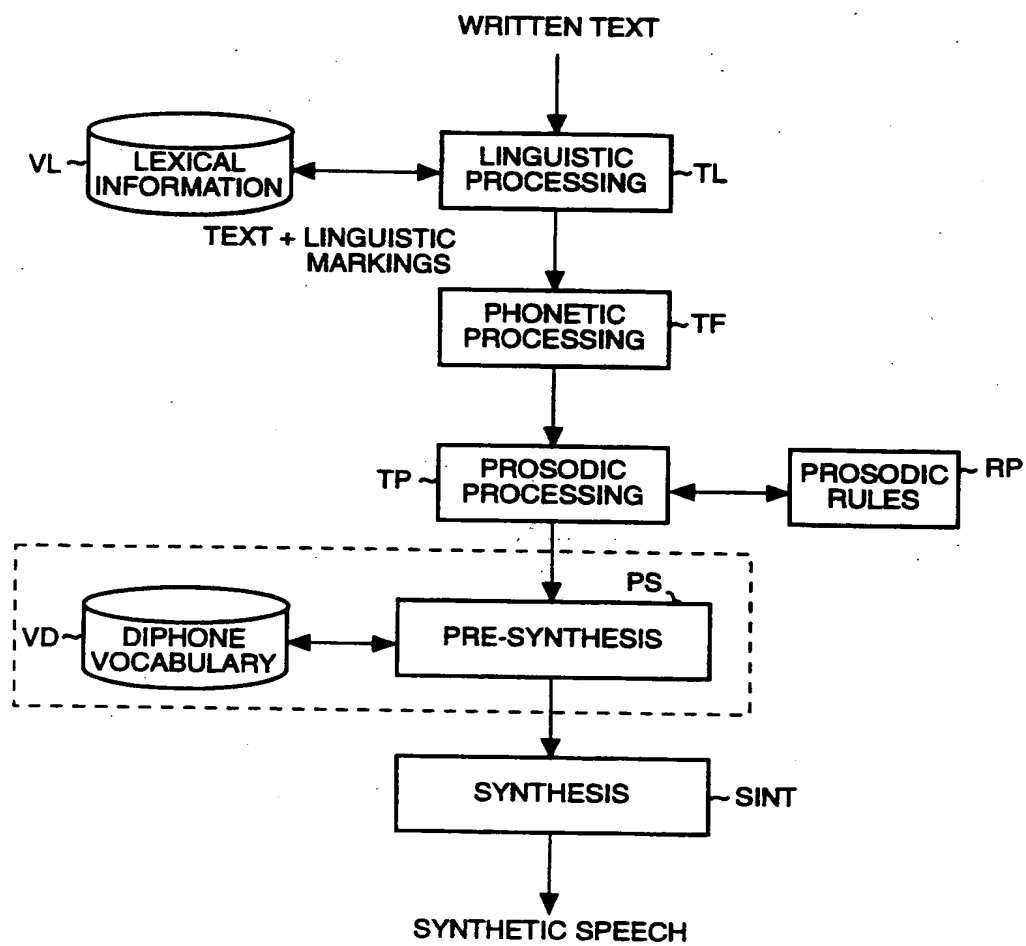


Fig. 1

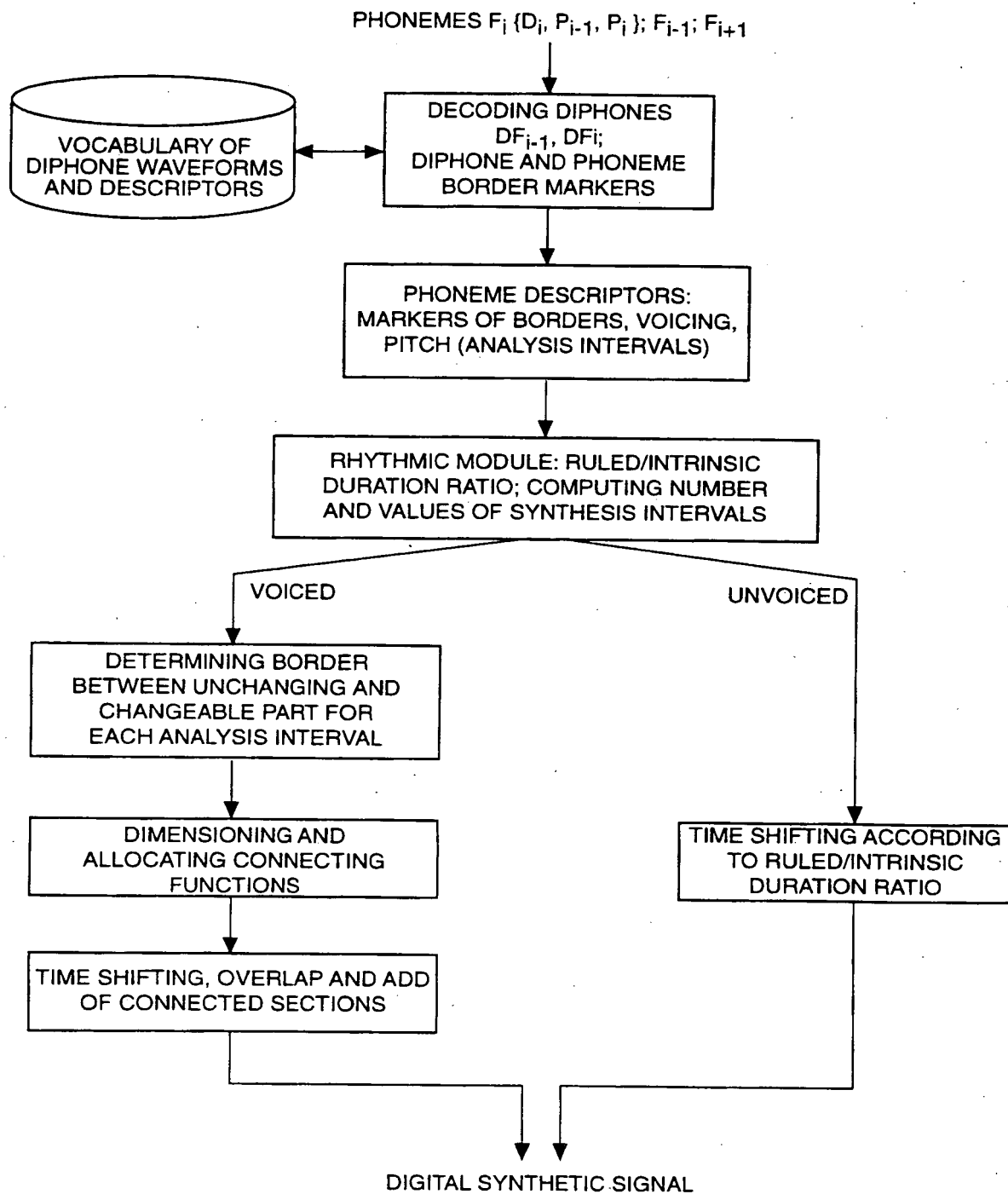


Fig. 2

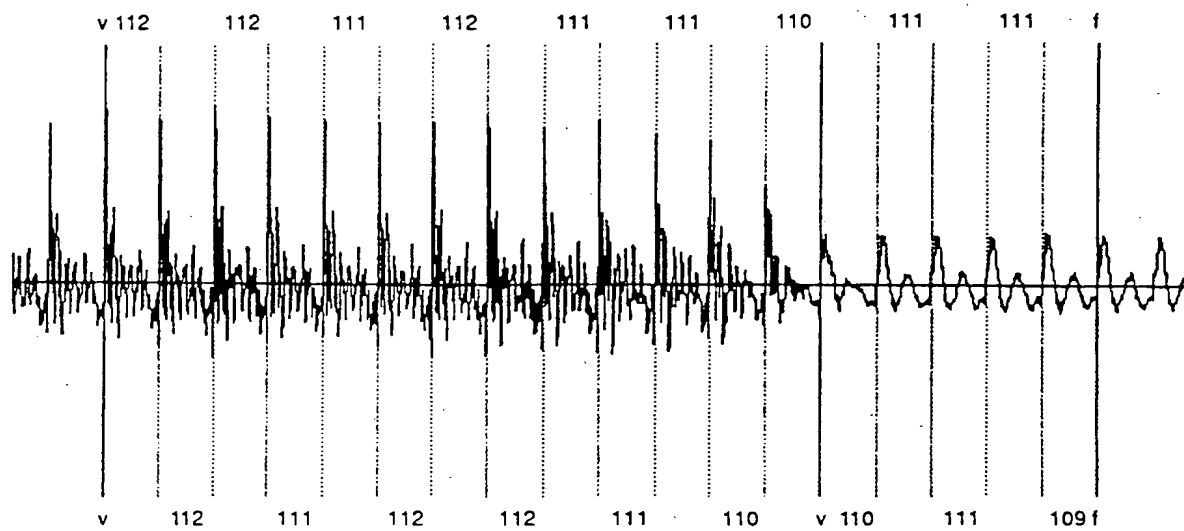


FIG. 3

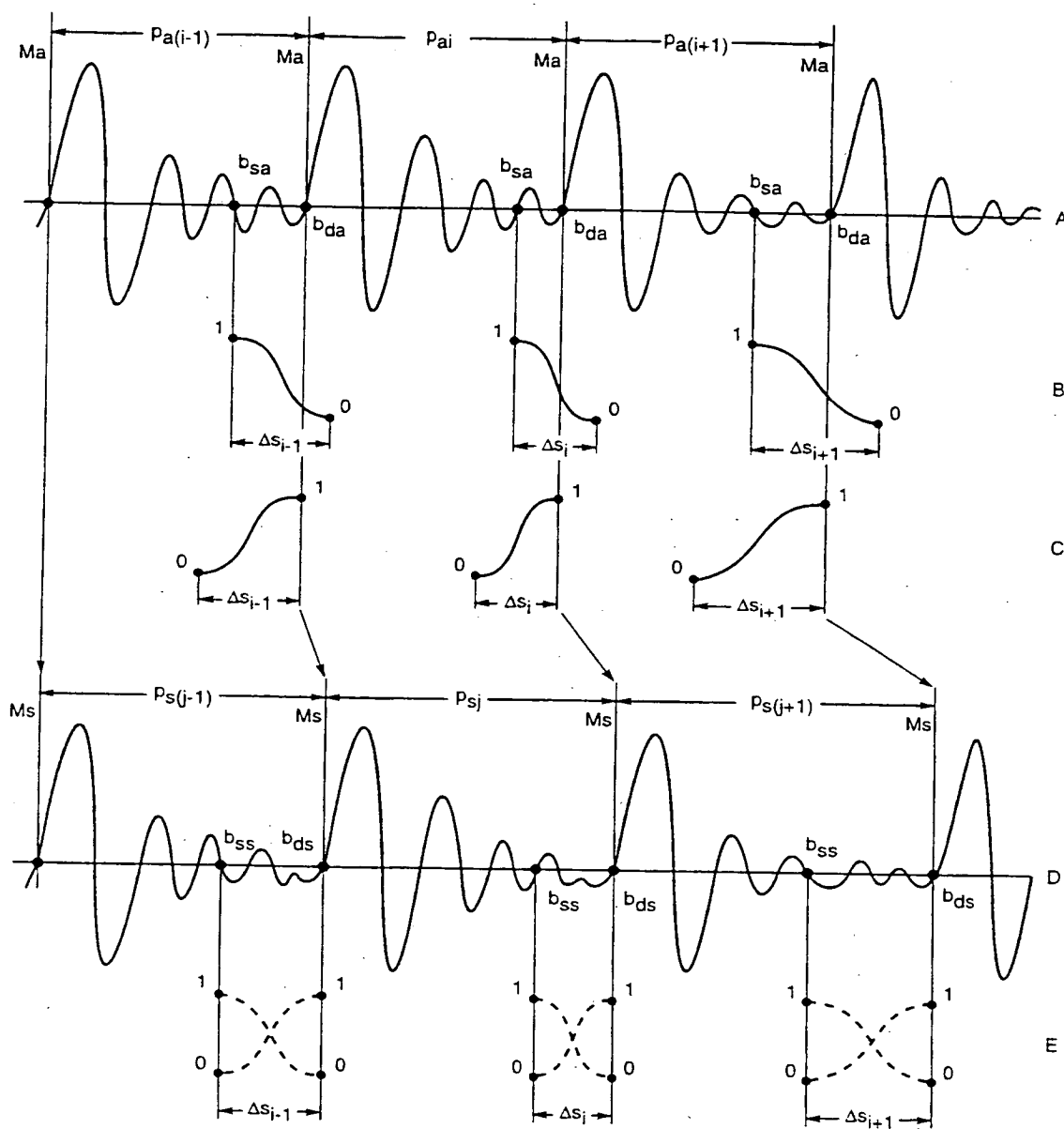


FIG. 4

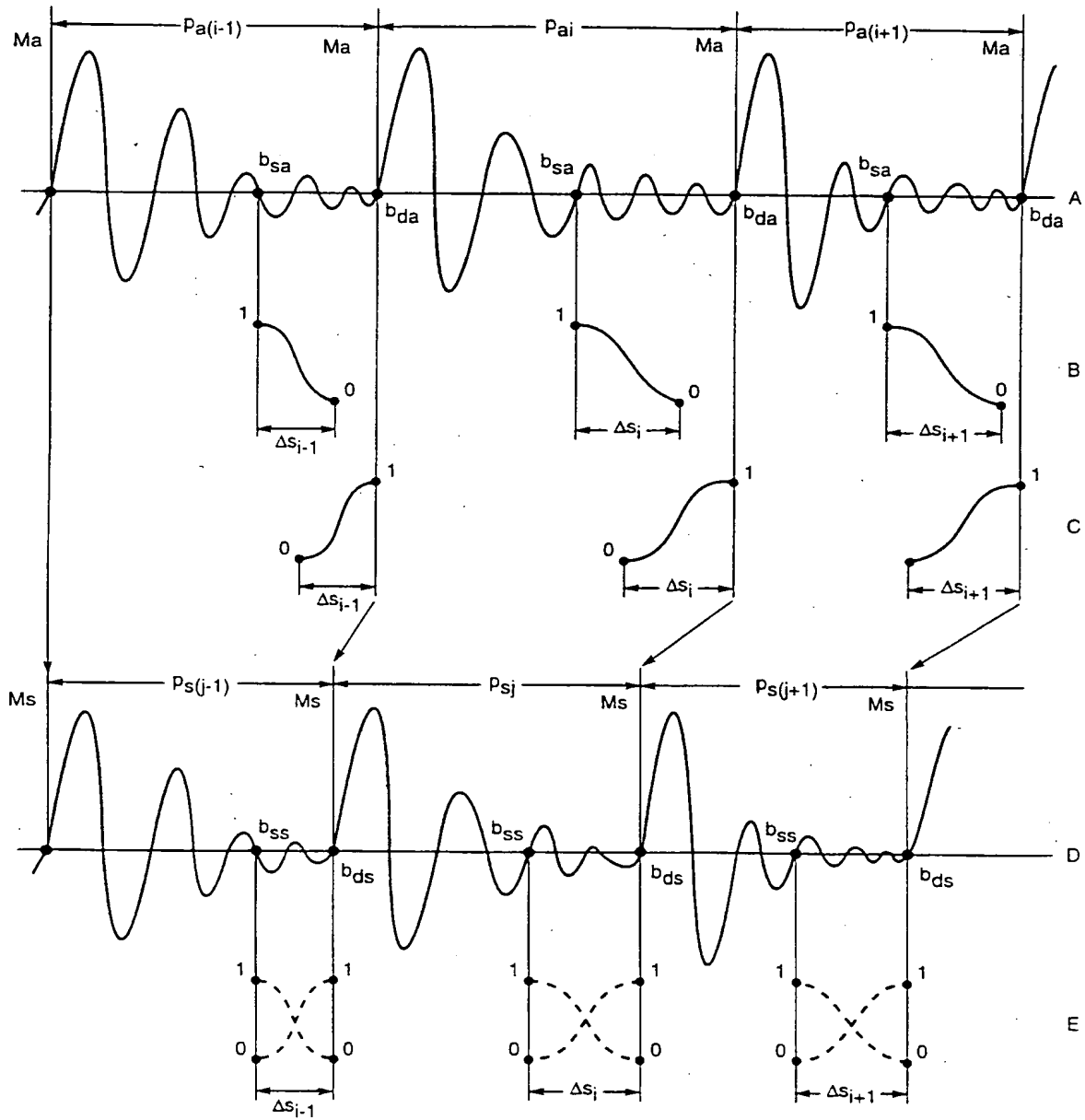


FIG. 5

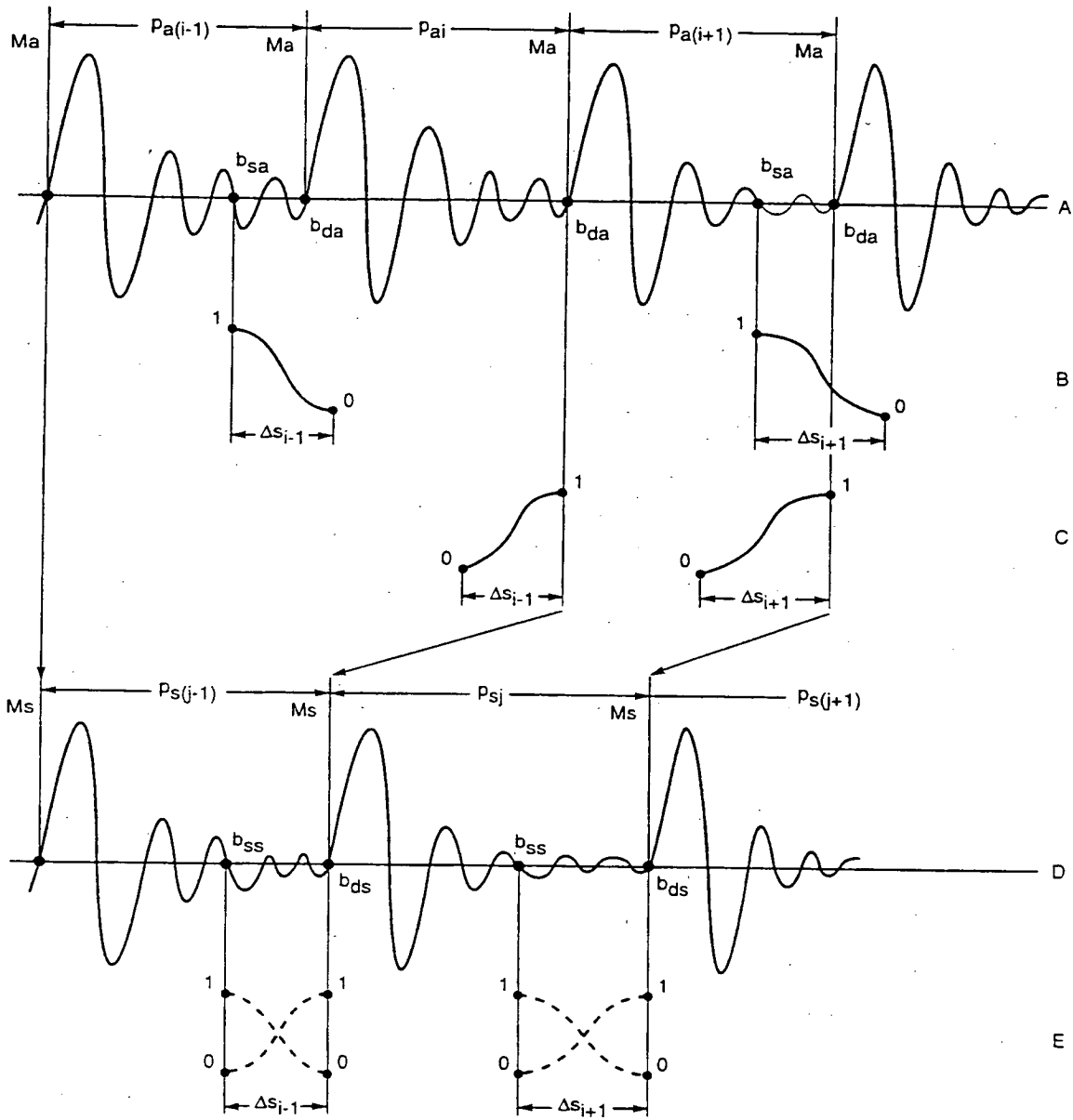


FIG. 6

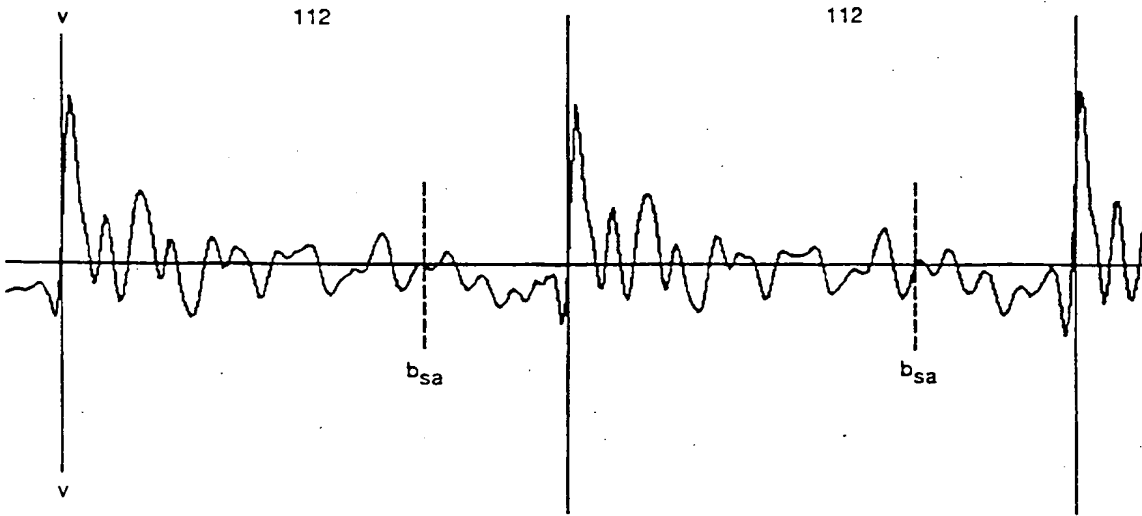


FIG. 7A

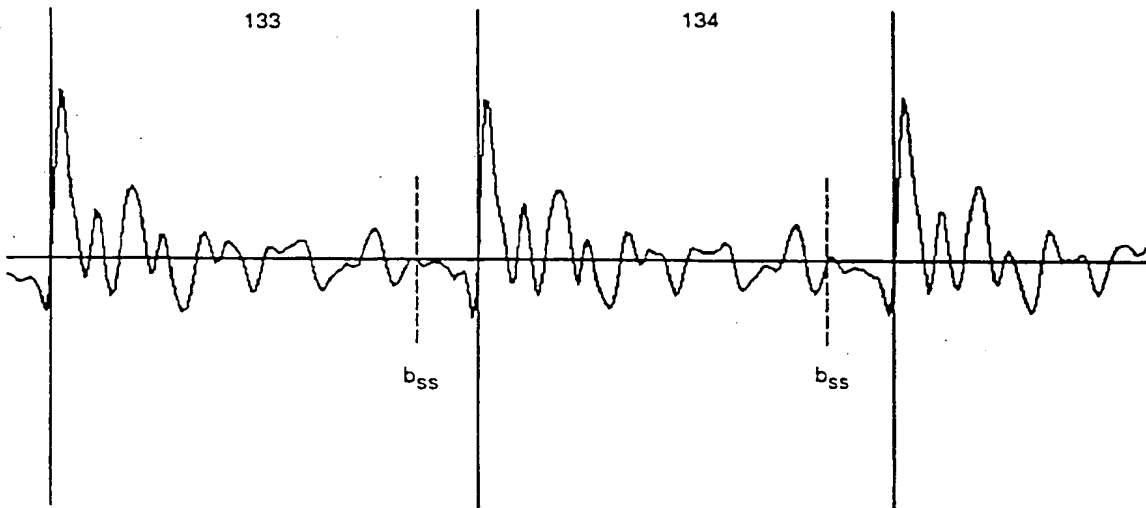


FIG. 7B

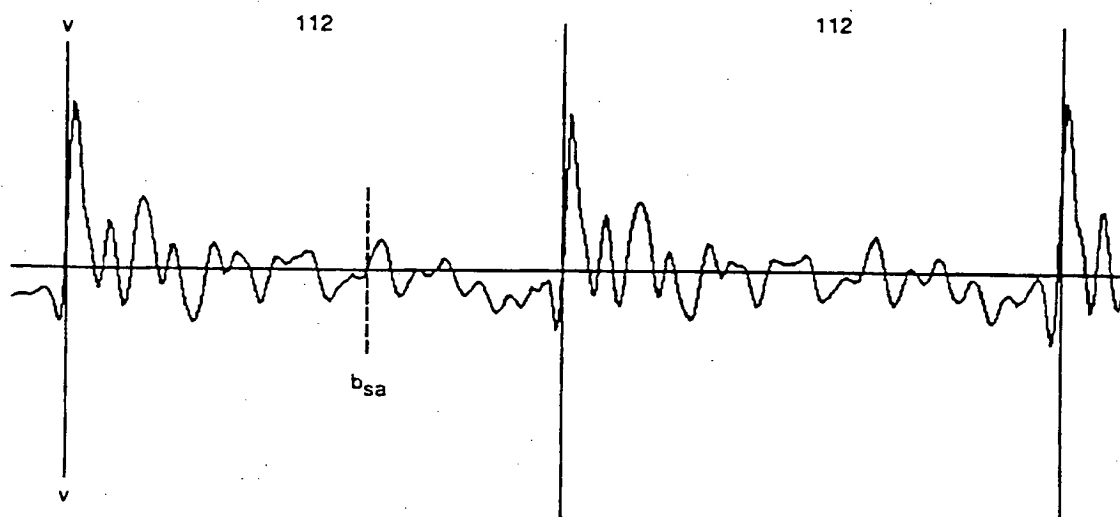


FIG. 8A

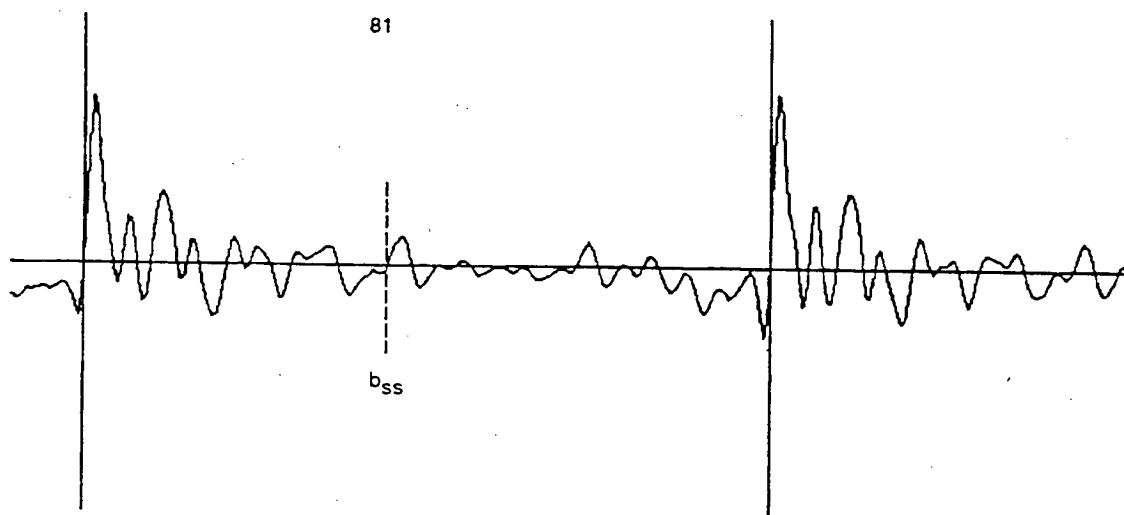


FIG. 8B

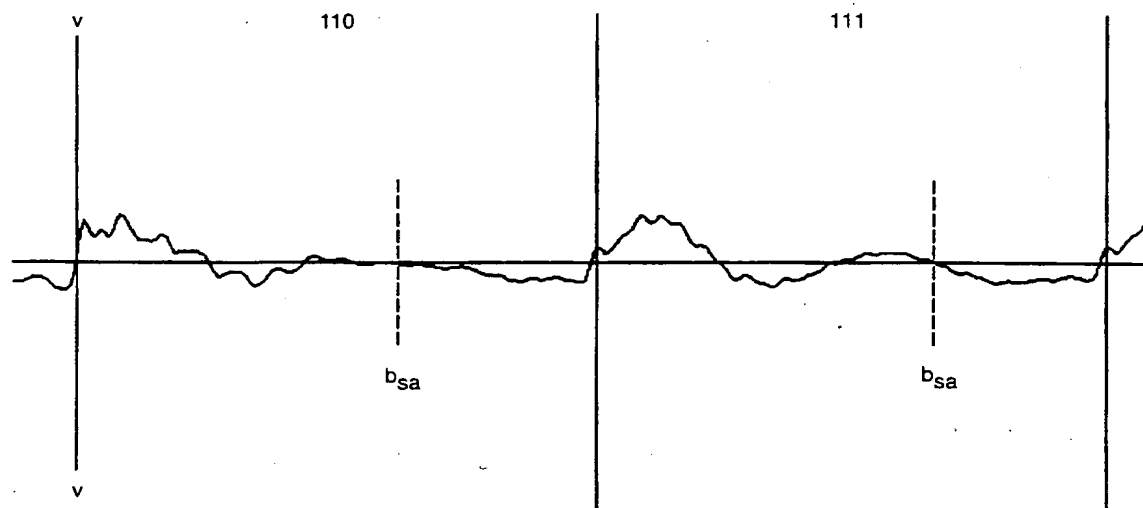


FIG. 9A

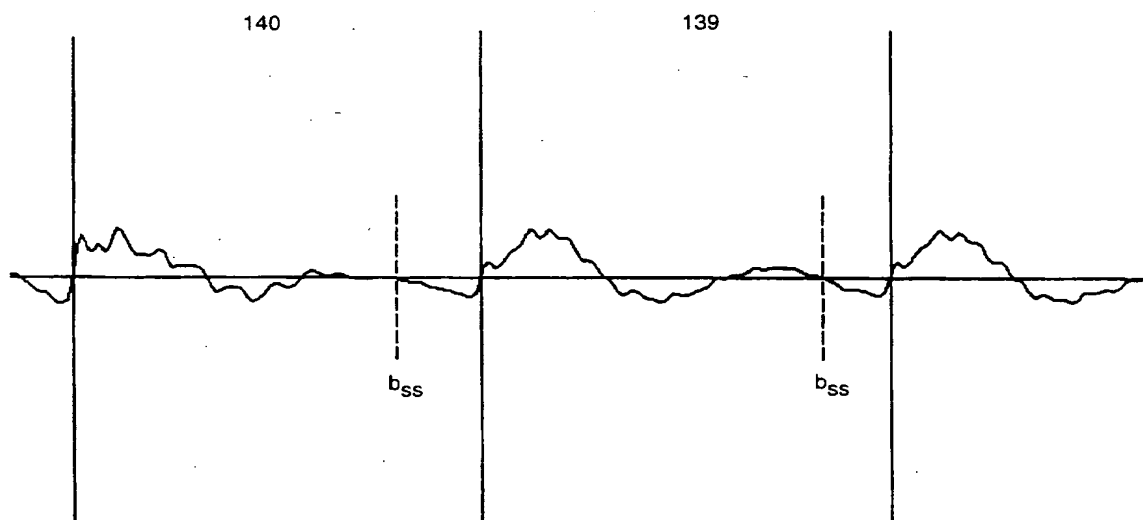


FIG. 9B

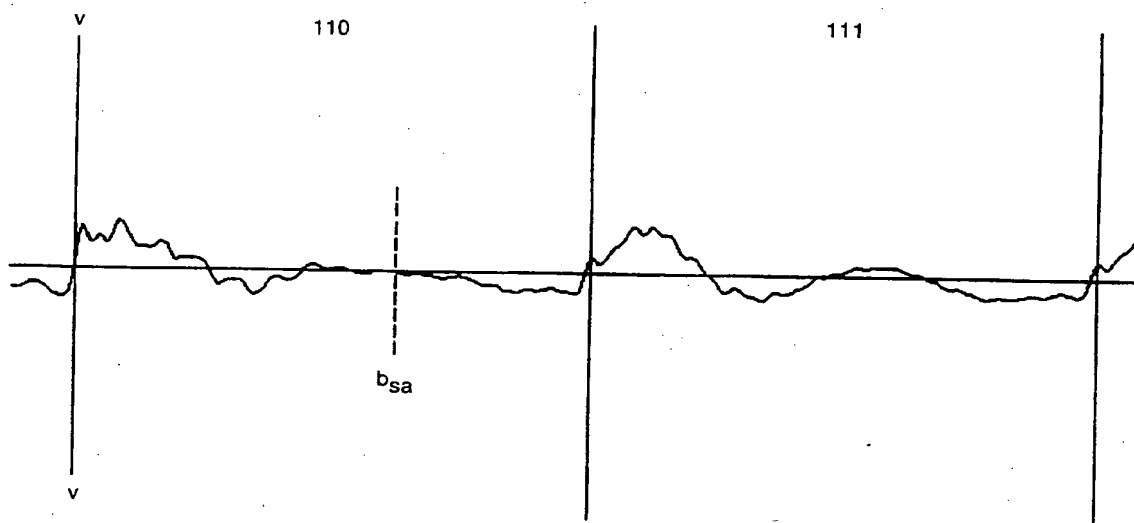


FIG. 10A

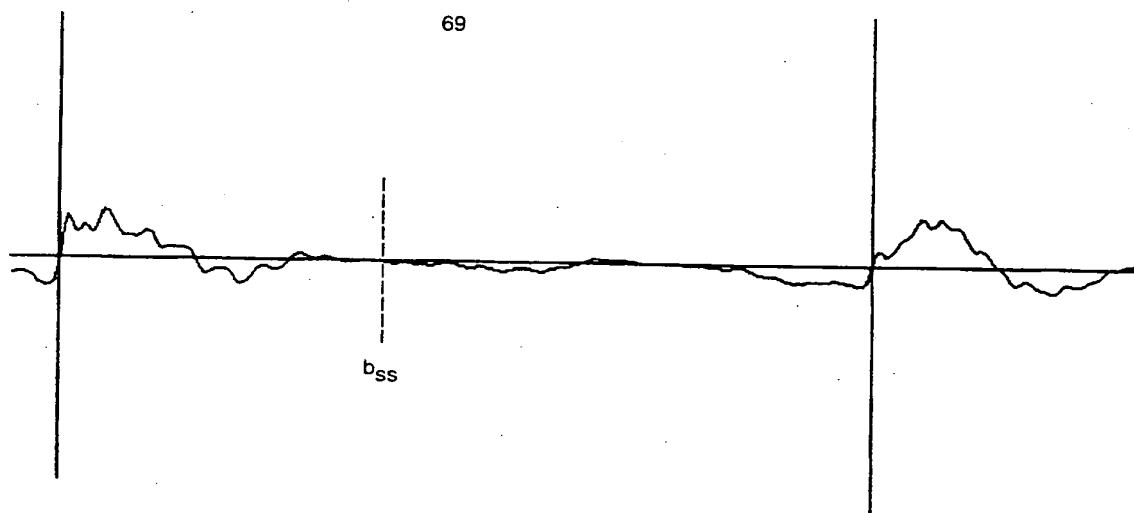


FIG. 10B

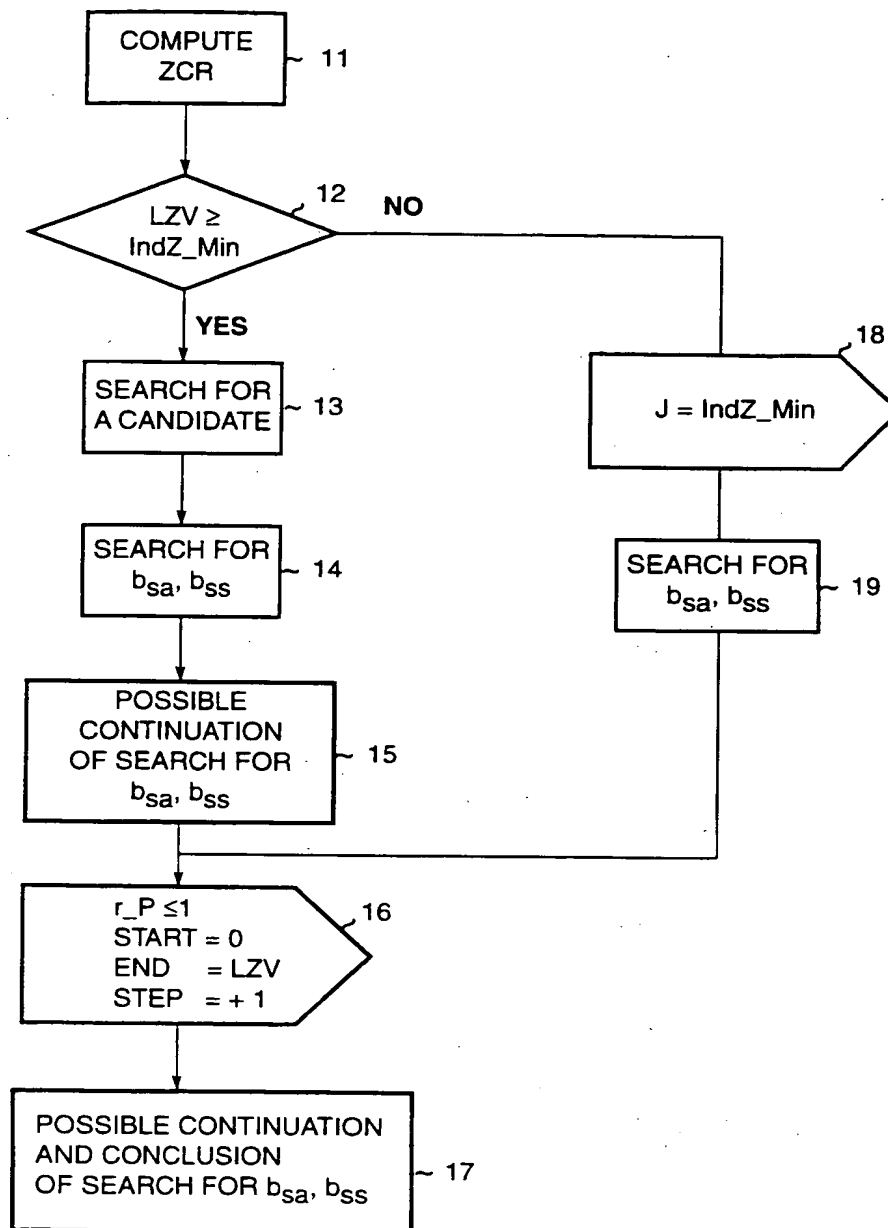


Fig.11

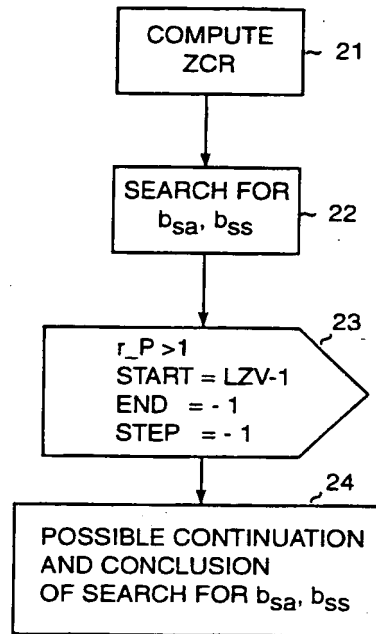


Fig.12

11 (21)

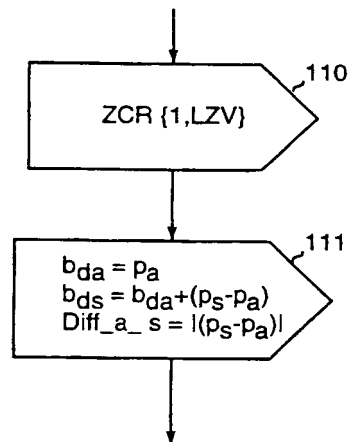


Fig.13

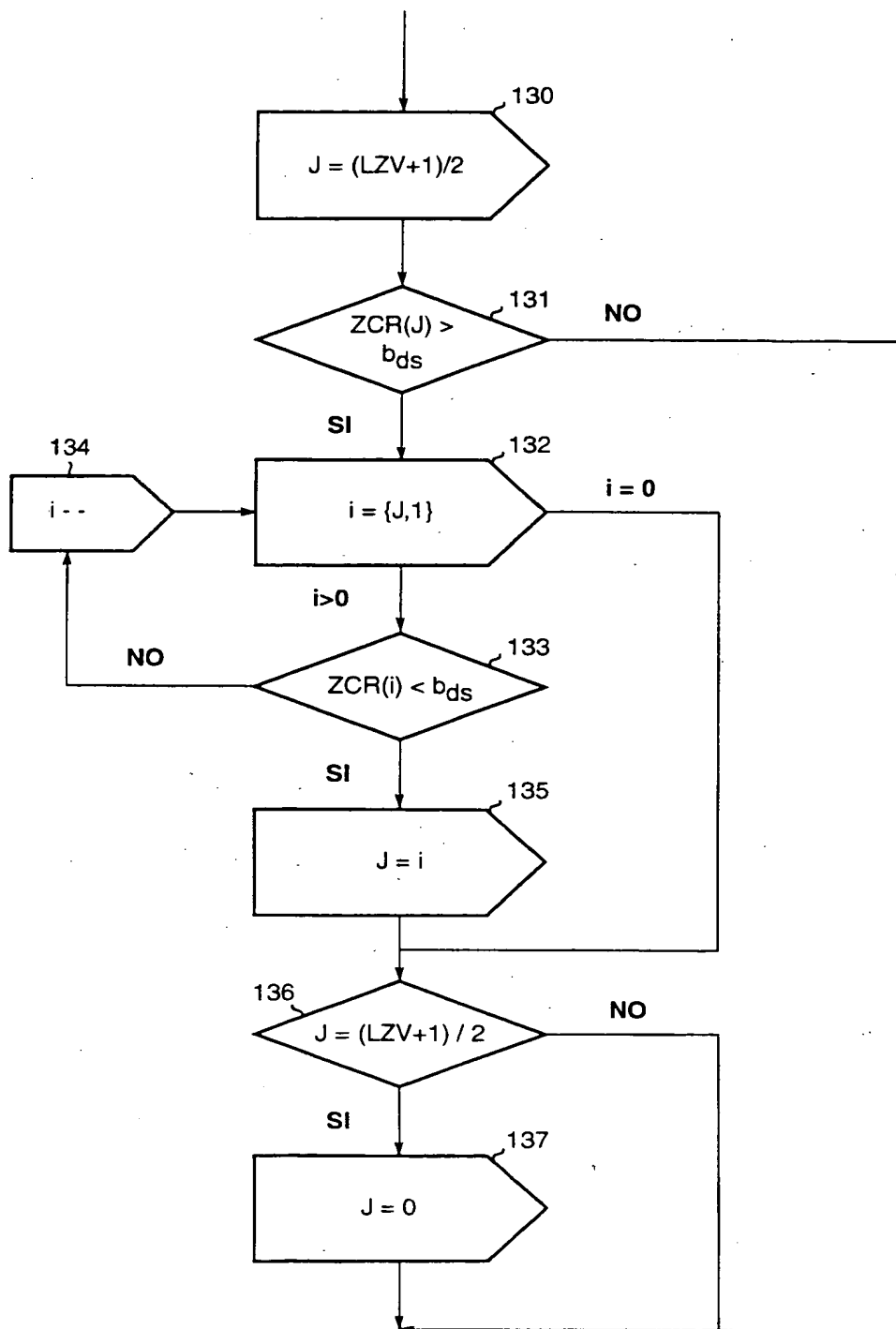


Fig.14

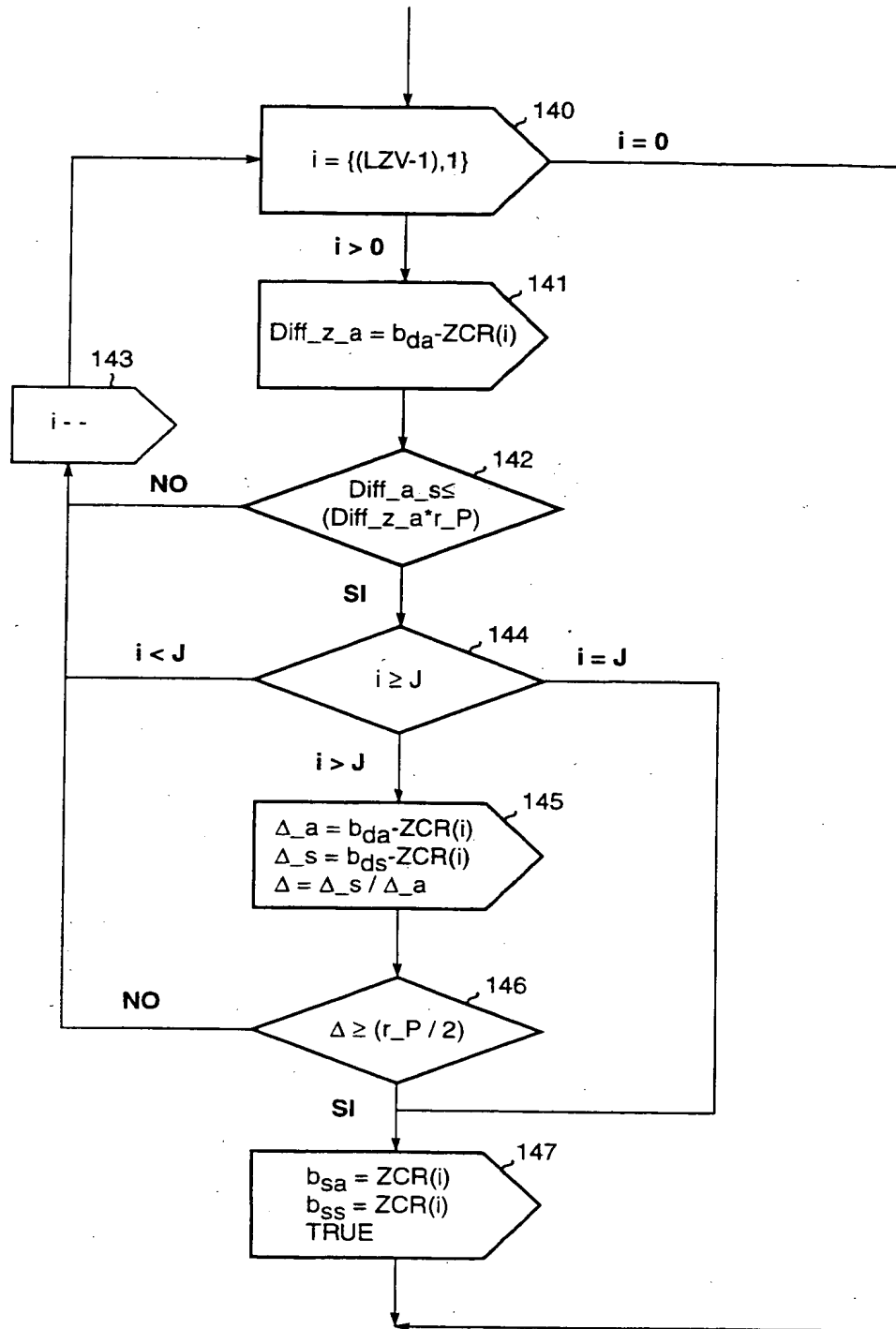


Fig.15

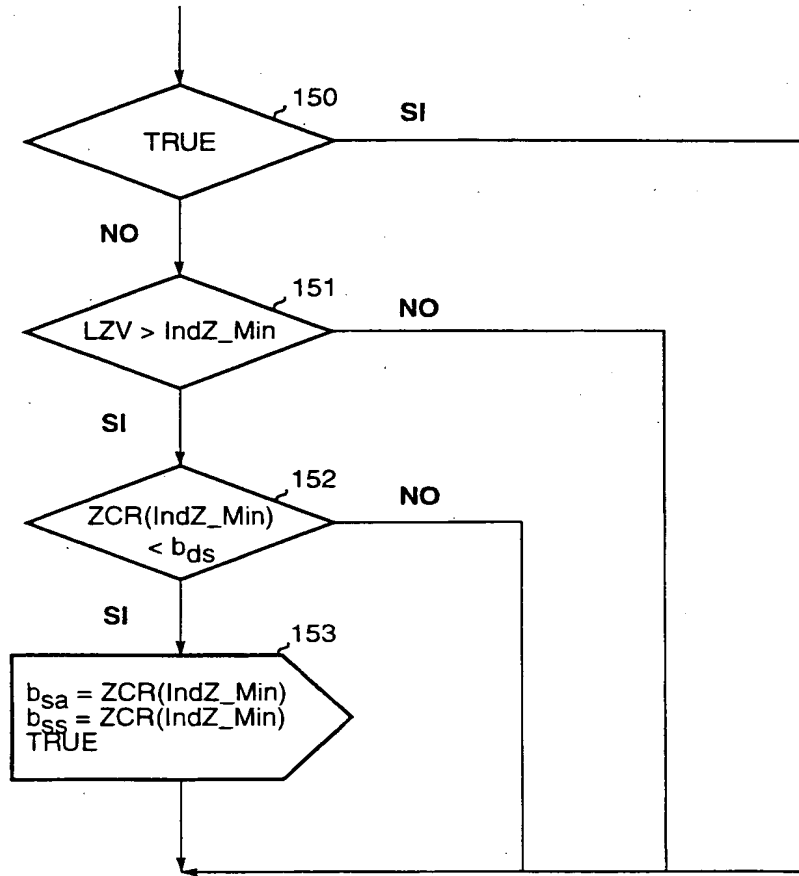


Fig.16

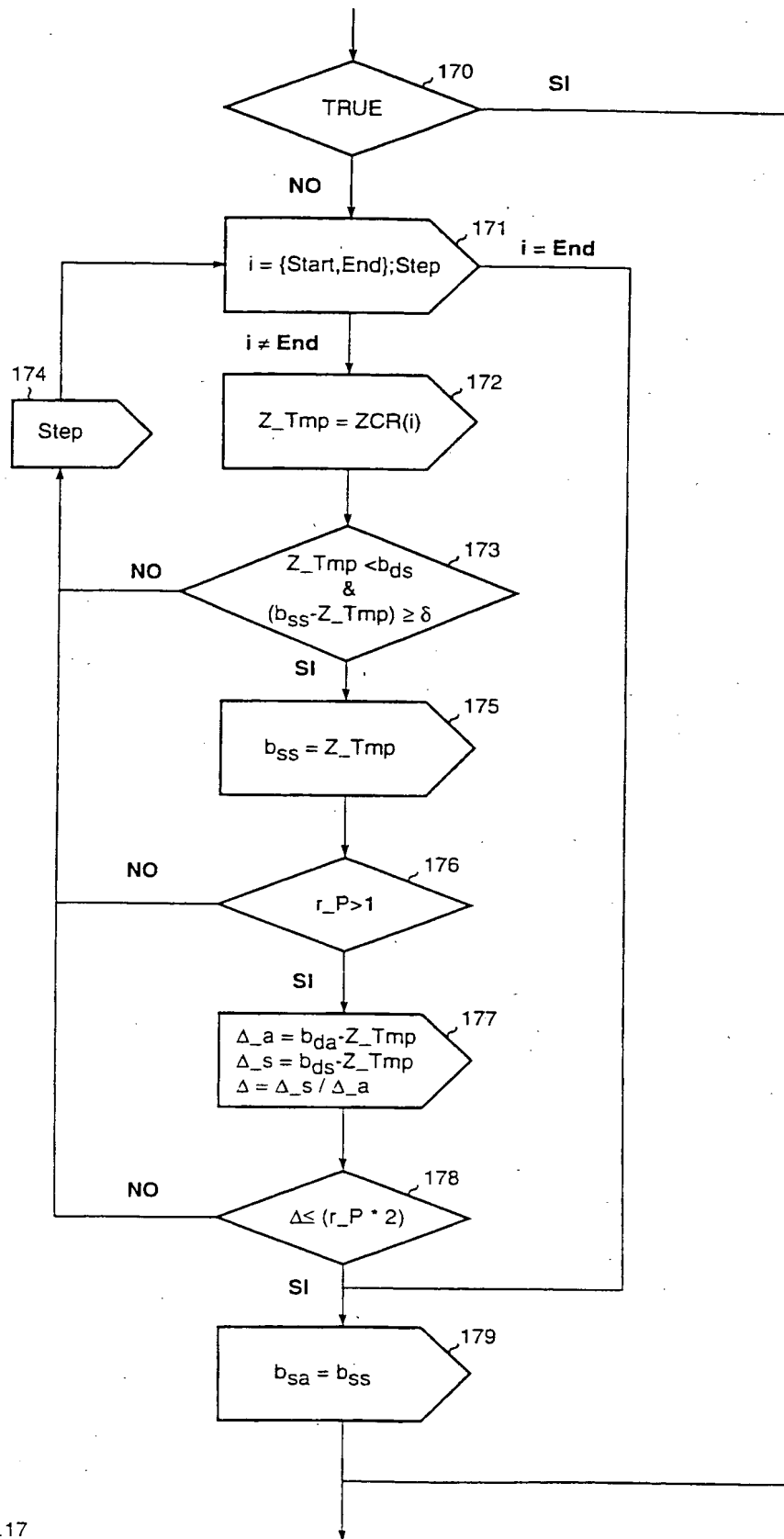


Fig.17

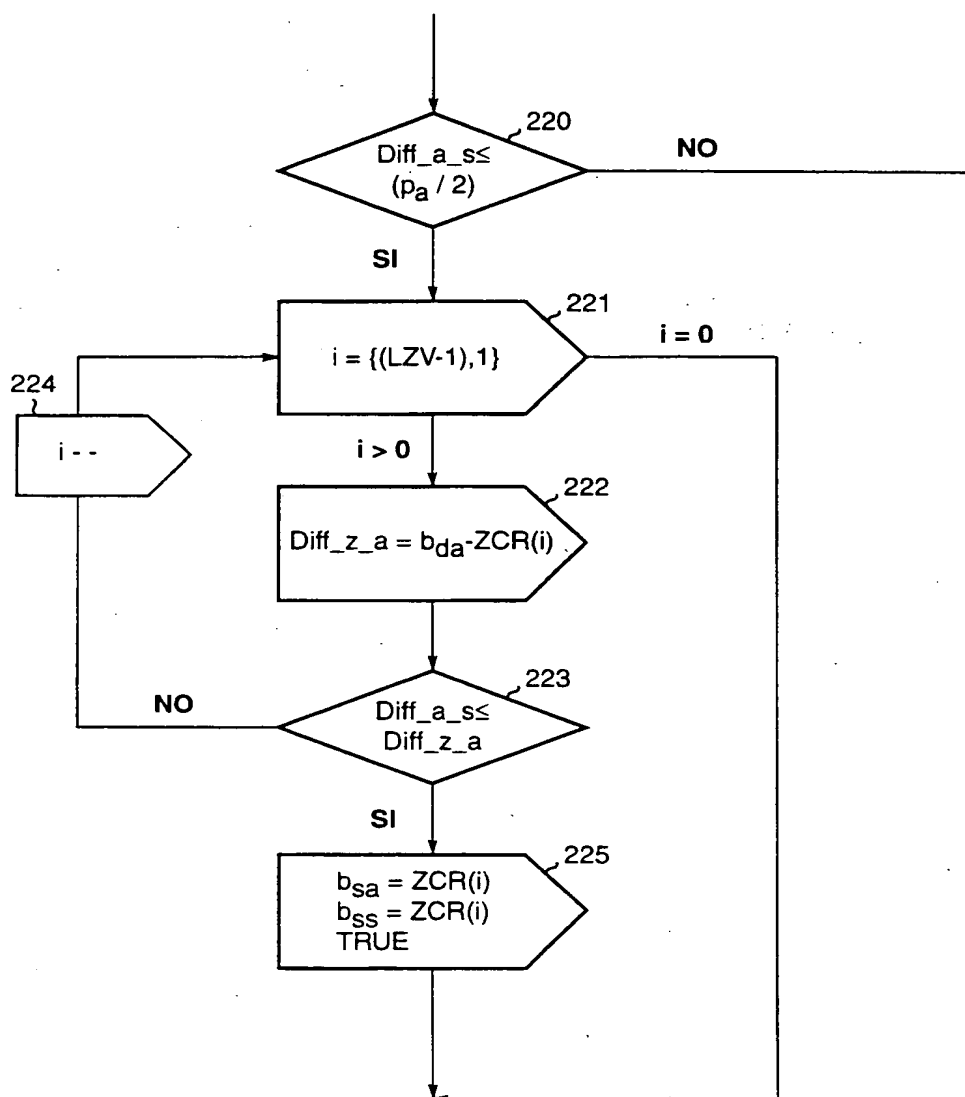


Fig.18

